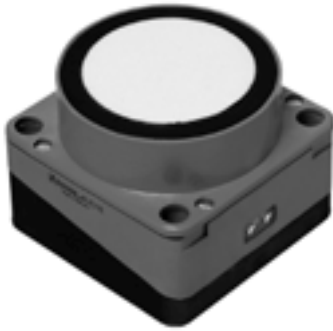**Ultrasonic sensor**
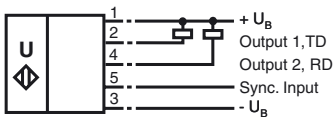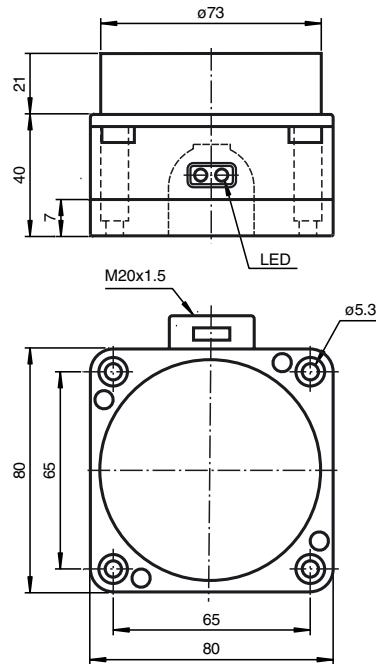# UC6000-FP-E7-R2-P5

Dimensions

Features

- 2 independent switch outputs
- Serial interface
- Switch point setting via DIP-switches or RS 232 interface
- Synchronisation options
- Temperature compensation
- Absolute polarity reversal protection
- Parameterisable with ULTRA 2001

Technical data

$C\epsilon$

General specifications

Sensing range	800 ... 6000 mm
Unusable area	0 ... 800 mm
Standard target plate	100 mm x 100 mm
Transducer frequency	approx. 65 kHz
Response delay	for factory setting
	minimal (EM; NONE): $\leq$180 ms (2 measuring cycles)
	default (EM, MXN, 5, 2): $\leq$360 ms (4 measuring cycles)
	dynamic (EM, DYN): $\leq$270 ms (3 measuring cycles)

Indicators/operating means

LED yellow	switching state switch output 1
	switching state switch output 2
LED red/green	permanently green : "Power on", flashes during standby operation
	red flashing : "Error", (e. g. background noise level too high)

Electrical specifications

Operating voltage	15 ... 30 V DC , ripple 10 %$_{SS}$
No-load supply current I_0	$\leq$ 60 mA

Interface

Interface type	RS 232, 9600 bit/s, no parity, 8 data bits, 1 stop bit

Input/Output

Synchronisation	1 synchronous connection, bidirectional
	0-level: $-U_B$ ... $(-U_B + 1\ V)$, 1-level: $(-U_B + 5\ V)$ ... $+U_B$
Pulse length	$\geq$ 100 μs
Pause length	$\geq$ 2 ms
Synchronisation frequency	$\leq$ 10 Hz , with external synchronisation

Output

Output type	2 switch outputs npn, normally open/closed
Resolution	< 1 mm
Repeat accuracy	$\leq$ 0,1 % of full-scale value
Rated operational current I_e	200 mA , short-circuit/overload protected
Voltage drop U_d	$\leq$ 3 V DC
Range hysteresis H	$\leq$ 1 % of the set operating distance
Temperature influence	$\leq$ 2 %

Standard conformity

Standards	EN 60947-5-2

Ambient conditions

Ambient temperature	-25 ... 70 °C (248 ... 343 K)
Storage temperature	-40 ... 85 °C (233 ... 358 K)

Mechanical specifications

Protection degree	IP65
Connection	terminal compartment, $\leq$ 2.5 mm^2 conductor csa
Material	
Housing	PBT
Transducer	epoxy resin/hollow glass sphere mixture; polyurethane foam
Mass	320 g

Electrical connection

Standard symbol/Connection:
(Version E7, npn)

1	$+U_B$
2	Output 1,TD
4	Output 2, RD
5	Sync. Input
3	$-U_B$

Notes

Description of the sensor functions

The outputs of the sensor can be used in two different operating modes: Switching mode with 2 adjustable switching points, or RS 232 mode (RS 232, 9600, n, 8, 1). Select the operating mode with DIP switch 10. The switching points are set with the DIP switches 1-4 and 5-8 (see table). Switch 9 is used to set the close or open function of the switch outputs.

For further information on the sensor's command set, please see the publication "Command Set for Ultrasonic Sensors with RS 232 Interface".

Caution: Ensure that DIP switch S10 is correctly set before connecting the RS 232 interface.

Synchronisation

The sensor features a synchronisation input for the suppression of mutual interference. If this input is not used, the sensor will operate using an internally generated clock rate. It can be synchronised by applying a square wave voltage. A falling edge leads to the transmission of a single ultrasonic pulse. A low level > 1 s or an open synchronisation input will result in the normal operation of the sensor. A high level > 1 s will result in the standby operation of the sensor (green LED).

Several functions are available:
- Two to five sensors can be synchronised by interconnecting their synchronisation inputs. In this case, the sensors alternately transmit ultrasonic pulses.
- Multiple sensors can be controlled by the same synchronisation signal. The sensors are synchronised.
- The synchronisation pulses are sent cyclically to individual sensors. The sensors operate in multiplex mode.
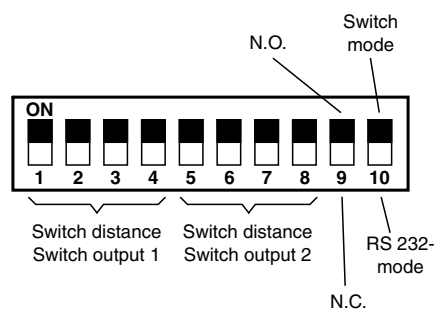
The response time increases when sensors are synchronised as the measuring cycle time is increased by the synchronisation.

Adjustment of the evaluation window via coding switch in terminal compartment

Switch 1 2 3 4	NDE [mm]	Switch 5 6 7 8	FDE [mm]
0 0 0 0	800	0 0 0 0	950
0 0 0 1	1100	0 0 0 1	1250
0 0 1 0	1400	0 0 1 0	1550
0 0 1 1	1700	0 0 1 1	1850
0 1 0 0	2000	0 1 0 0	2150
0 1 0 1	2300	0 1 0 1	2450
0 1 1 0	2600	0 1 1 0	2750
0 1 1 1	2900	0 1 1 1	3050
1 0 0 0	3200	1 0 0 0	3350
1 0 0 1	3500	1 0 0 1	3650
1 0 1 0	3800	1 0 1 0	4000
1 0 1 1	4200	1 0 1 1	4400
1 1 0 0	4600	1 1 0 0	4800
1 1 0 1	5000	1 1 0 1	5200
1 1 1 0	5400	1 1 1 0	5600
1 1 1 1	5800	1 1 1 1	6000

1 ≙ ON, 0 ≙ OFF

DIP Switches in Terminal Compartment

N.O.
Switch mode

ON
1 2 3 4 5 6 7 8 9 10

Switch distance Switch output 1
Switch distance Switch output 2
N.C.
RS 232-mode

Model number

UC6000-FP-E7-R2-P5

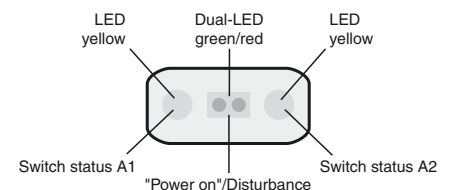## Characteristic curves/additional information

Characteristic response curves

Curve 1: flat surface 100 mm x 100 mm
Curve 2: round bar, Ø 25 mm

LED-Window

LED yellow
Dual-LED green/red
LED yellow
Switch status A1
"Power on"/Disturbance
Switch status A2

Accessories

Mounting aid
MH 04-3505

Mounting flange
PA02

Interface-cable
UC-FP/U9-R2

Service program
ULTRA 2001

Thanks to its extensive command set, the sensor can be configured to suit the application via the RS 232 interface.

RS 232 command set (overview)

Command	Meaning	Parameter	Access
VS0	**V**elocity of **S**ound at **0** °C	VS0 in [cm/s]	read and set
TO	**T**emperature **O**ffset	TO in [0.1K]	read and set
TEM	**TEM**perature	TEM in [0.1K]	read and adapt to TO
REF	**REF**erence measurement	REF distance in [mm]	adaptation of VS0
VS	**V**elocity of **S**ound	VS in [cm/s]	read
UDS	**U**se **D**IP **S**witches	UDS binary [0/1]	read and set
SD1[1]	**S**witching **D**istance **1 1**	SD11 distance in [mm]	read and set
SD12	**S**witching **D**istance **1 2**	SD12 distance in [mm]	read and set
SD2[1]	**S**witching **D**istance **2 1**	SD21 distance in [mm]	read and set
SD22	**S**witching **D**istance **2 2**	SD12 distance in [mm]	read and set
SH1	**S**witching **H**ysteresis **1**	Hysteresis in [%]	read and set
SH2	**S**witching **H**ysteresis **2**	Hysteresis in [%]	read and set
BR	Unusable area (**B**lind **R**ange)	Unusable area to [mm]	read and set
RR	**R**ange **R**eduction	Unusable area from [mm]	read and set
NEF	**N**o **E**cho is **F**ailure	1: "no echo" is failure; 0: "no echo" is not failure	read and set
FSF	**F**ail **S**afe **F**unction	Shutdown function in event of failure	read and set
CBT	**C**onstant **B**urst **T**ime	Burst time in [µs]	read and set
CCT	**C**onstant **C**ycle **T**ime	Time in [ms]	read and set
SSY	**S**tartup **SY**nchronised	SSY binary [0/1]	read and set
FTO	**F**ilter **T**ime**O**ut	Number of measurements without echo to be filtered	read and set
EM	**E**valuation **M**ethod	Evaluation method { 0 = NONE; PT1[,f,p,c]; MXN[,m,n]; DYN[,p] }	read and set
CON	**CON**servative filter	Counter threshold as number	read and set
OPM	**O**peration **M**ethod	Switch output operating mode { S,R,W,L,H } analogue output { S,L }	read and set
OM	**O**utput **M**ode	OM coded [close NO = 0, open NC = 1]	read and set
MD	**M**aster **D**evice	Function as master {0 = NONE},AD,RD,RT,SS,ATB,RDB,RTB }	read and set
DIP	**DIP** switch settings	DIP switch setting as hexadecimal string	read
AD	**A**bsolute **D**istance	Distance in [mm]	read
RT	**R**un**T**ime	Echo run time in machine cycles [1 machine cycle = 1.085µs]	read
SS1	**S**witching **S**tate **1**	SS1 binary [0: inactive, 1 active] (independent of OM)	read
SS2	**S**witching **S**tate **2**	SS2 binary [0: inactive, 1 active] (independent of OM)	read
ADB	**A**bsolute **D**istance **B**inary	Distance in [mm], binary	read
RTB	**R**un**T**ime **B**inary	Echo run time in machine cycles [1 machine cycle = 1.085µs], binary	read
ER	**E**cho **R**eceived	Echo detected: no, yes [0/1]	read
VER	**VER**sion	Version string: xxxx	read
ID	**ID**entification	ID string: P&F UC...-..-E6/E7-R2 Eprom: xxxx Version yyyy	read
DAT	**DAT**e	Date string: e.g. Date: 06/11/96 Time: 16:14:26	read
ST	**ST**atus	Status as hexadecimal string	read
RST	**R**e**S**e**T**	Performs a reset	Command
DEF	**DEF**ault settings	Restores defaults	Command
SUC	**S**tore **U**ser **C**onfiguration	Stores all settings	Command
RUC	**R**ecall **U**ser **C**onfiguration	Restores stored settings	Command

Programming instructions

Caution: When programming the sensor via the integrated RS 232 interface, ensure that DIP switch 10 is in the OFF (RS 232 mode) position before connecting the interface cable.

Electrical connection of interface cable UC-FP/U9-R2 (see accessories).

Interface cable Conductor colour	Sensor terminal compartment Terminal no.
brown (TD)	4 (RD)
black (RD)	2 (TD)
blue (GND)	3 ($-U_B$)

Structure of the filter functions

```
                    ┌─────────────────────────────┐
                    │ Propagation time measurement │
                    └─────────────────────────────┘
                                   │
                                   ▼        FTO
                    ┌─────────────────────────────┐
                    │       Timeout filter         │
                    └─────────────────────────────┘
                                   │
          EM, DYN                EM, PT1                EM, MXN
    ┌───────────────────┐  ┌─────────────────┐  ┌───────────────────────────┐
    │ Dynamic evaluation│  │ Low-pass filter │  │ Calculation of the mean value │
    └───────────────────┘  └─────────────────┘  └───────────────────────────┘
                                   │
                                   ▼                CON
                    ┌─────────────────────────────┐
                    │       Output filter          │
                    ├──────────────┬──────────────┤
                    │ Conservative │   Sliding     │
                    └──────────────┴──────────────┘
                                   │          OPM
                                   │          OM
                    ┌─────────────────────────────┐
                    │           Output             │
                    └─────────────────────────────┘
```

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